XMP 120 – modular and therefore flexible in use



A press-in unit with huge modularity. The XMP, which is designed from standardised components, is based on a modular principle and provides a flexible solution for your assembly process for simple as well as for complex tasks.

XMP, the electromechanical press-in unit with the "X" – the crossover of experience and innovation combines the best of the QMP and SMP series with future-oriented press-in technology.

Gear modules for a process optimized movement speed.

Offers many possibilities like e.g. mounting of a customers motor and configuration with motor holding brake, holding brake or backstop.



The space-saving <u>control system</u> with integrated servo controller is used for the evaluation of curves and their documentation as well as for the control of the XMP press-in unit.

Thanks to the variability of our press-in procedures, you have a high-performance system for the use in the quality critical assembly.

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Fast system integration and error-free setup.
The decentralised intelligence of the XMP transmits the characteristic data via Plug-and-Play.

For a visual support during the assembly the large illuminated field shows the process status, the direction of movement and the position of the plunger.

Absolute stroke / length measuring system makes a reference movement unnecessary.

Different variants of the load cell, also available as redundant version.





Technical data sheet Press-in unit XMP series





Max. force, nominal load	30 / 50 / 75 / 100 kN								
Drive motor	electronically controlled, maintenance-free servo motor								
Motor mounting	180° turned with offset ge								
Options motor	Motor holding brake (e.g. hold tool Execution customer moto								
Stroke	200 mm / 400 r								
Nominal speed	Motor 1M + Gear 3Z 500 mm/s (max. 30,0 kN) Motor 2M + Gear 3Z 320 mm/s (max. 50,0 kN) Motor 1M + Gear 5Z 270 mm/s (max. 50,0 kN) Motor 2M + Gear 5Z 170 mm/s (max. 100,0 kN)								
Holding time	max. 2,5 s with backstop any time with holding brake max. 999 s								
Executions load cell	KU: Bottom, in the plunger RU: Bottom, in the plunger, redundant								
Measurement direction	DR: Pres DZ: Press and pu								
Measuring principle	Digital DMS technology, drift-free force measuremen								
Accuracy force measurement	$0.5\ \%$ of the final value								
Execution stroke/length measurement	Absolute stroke measuring system, enables absolute and relative stroke measuremen								
Stroke/length repeat accuracy	< 0,01 mm (by about 20 mm/s)								
Resolution	0,003 mm								
Plunger	Recirculating ball screw; non-rotating plunger								
Max. weight of additional tool	15 kg / 50 kg with motor holding brake								
Assembly	Face side, screws and centering via fitting colla installation position vertical / horizoni								
Service	Low maintenance: Lubrication interval 600.000 cycles; Repair-friendly: Certain components can be replaced by the user without adjustment.								

Designation, size press-in unit		Force [kN]		Stroke [mm]		Motor		Gear		Measurin direction		Option		Force measuring		Option to combine	Plunger
XMP 120	/	50	-	200	-	2M	-	5Z	-	DR ·	-	MB	-	KU	-	00 -	00
Example		30 50		200 400		1M 2M		3Z 5Z		DR DZ		MB HB		KU RU		MB HB	99
		75				0M		0Z				RS				RS	
	-	100				ΚM						SL				SL	
												LE				LE	

834 mm

mm

KM = Customer motor 3Z = 500 mm/s (1M) / 320 mm/s (2M)5Z = 270 mm/s (1M) / 170 mm/s (2M)0Z = Special gear DR = Press DZ = Press and pull 00 = Standard MB = Motor holding brake HB = Holding brake RS = Backstop

1M = Motor BSR48130 2M = Motor HBR63150 + MB 0M = Special motor

SL = Sealing air connection LE = Fan unit

KU = Force bottom (in the plunger) RU = Force bottom redundant

99 = Special



